COMPUTER CONTROLLED PAN-TILT UNIT Models PTU-D46



Directed Perception, Inc.

1485 Rollins Road, Burlingame, California 94010 (650) 342-9399 • FAX: (650) 342-9199 email: info@DPerception.com • website: http://www.DPerception.com

COMPUTER CONTROLLED PAN-TILT UNIT Models PTU-D46-17 & PTU-D46-70

Technical Specifications

General Features

- Simple to use from any RS-232 terminal or computer
- Fast and accurate camera positioning at low cost
- Precise control of position, speed & acceleration
- Small form factor
- Allows on-the-fly position and speed changes
- Self calibration upon reset
- Power consumption can be controlled from host
- ASCII command mode for simplicity, binary commands available for efficient program control
- DC power input from an unregulated source
- · Radiation hardened
- CE Mark certified for Europe

Pan-Tilt Performance

MODEL	PTU-D46-17	PTU-D46-70
Rated payload	6 lbs (2.72kg)	9 lbs (4.08kg)
Max. unloaded speed (@30VDC)	300°/second	60°/second
Resolution	3.086 arc minutes (0.051428°)	0.771 arc minutes (0.012857°)

Acceleration/Deceleration: Trapezoidal. On-the-fly speed and position changes.

Tilt Range (approx): minimum 31° up and 47° down (78° range) with option of 80° down (111° range)

Pan Range (approx): $\pm 159^{\circ}$ (318° range) with option of $\pm 180^{\circ}$ (360° range)

Power Requirements

Input Voltage: 8-30VDC unregulated

Power Consumption:

13W continuous peak (full-power mode) 6W continuous peak (low-power mode) 1W continuous peak (holding power off mode)

Mechanical

Pan-Tilt Unit:

- Weight: 3 lb.
- **Dimensions:** 3" wide x 5.13" high x 4.25" deep
- **Camera mounting:** Hole for 1/4-20 screw standard. Camera mounting plate removes for easy customizing.
- **Pan-tilt unit mounting:** Bottom or front 1/4-20 mounting

Controller:

- Weight: 8 oz.
- **Dimensions:** 3.25" wide x 4.5" long x 1.25" high

Specifications subject to change without notice.

Built-In Connectivity Capabilities

Basic Mode: Host RS-232 port controls single pan-tilt unit **Extended Mode:** Control of multiple pan-tilt units from one or more host computers. Multidrop RS-485 network using RJ-12.

Host Control

Host: RS-232 (default is 9600 baud, 1 start bit, 8 data bits, 1 stop bit, no parity, no handshaking). DB-9 female connector.

Host modes: Interactive Mode (ASCII command set) and Encoded Mode (binary format for higher bandwidth computer control)

Commands include:

<axis> is T for the tilt axis or P for the pan axis.

Axis Control Commands:

General form: <axis><command><value><delim> ⇒ [<status>]

Go to position: $\langle axis \rangle P \langle position \rangle \langle delim \rangle \Rightarrow [\langle status \rangle]$

Go to offset position: <axis>**O**<relative position><delim $> \Rightarrow [<$ status>]

Set target speed: $<axis>S<positions/sec><delim> <math>\Rightarrow$ [<status>] Set acceleration: $<axis>A<positions/sec^2><delim> <math>\Rightarrow$ [<status>]

Set speed bounds: <axis>[$\stackrel{\cdot}{U}$ | $\stackrel{\cdot}{L}$]<positions/sec><delim $> \Rightarrow$ [<status>]

Move power mode:

<axis>**M**[<hi power> | <reg power> | <lo power>]<delim> \Rightarrow [<status>]

Hold (stationary) power mode:

 $<axis>H[<reg power> | <lo power> | <power off>]<delim> <math>\Rightarrow$ [<status>]

Axis Queries:

General form: <axis><command><delim> ⇒ <query answer>

(Axis Control Commands become queries when the <value> argument is omitted.)

Resolution: <axis>>R<delim> \Rightarrow <arc seconds per position> **Position bounds:** <axis>>[N | X]<delim> \Rightarrow <boundary position>

Unit Commands:

Command menu: ?<delim> ⇒ <menu>
Await completion: A<delim> ⇒ <status>
Reset unit: R<delim> ⇒ [<status>]
Immediate mode: I<delim> ⇒ [<status>]
(immediate position command execution)

Slaved mode: S<delim>⇒ [<status>]

(position commands execute upon Await Completion command) **Defaults:** D[<save> | <restore> | <factory settings> | <delim> ⇒ [<status>]

(Saves and restores unit defaults at power up)

Available Options

- International AC/DC Power Supply (model PT-PS-INT30V)
- Weatherized option provides outdoor use (add "W" to PTU model)
- Nodal (gimbal) pan-tilt adaptor
 - Payload can mount at the intersection of the pan and tilt axes
 - Uses include rotating camera at focal point & mirror positioning
- C Programmer's Interface (model PTU-CPI)
- PTU network cabling kits available
- Trackball and analog joystick interfaces available

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